#### COT 6405 Introduction to Theory of Algorithms

#### Topic 15. Minimum Spanning Tree

# Minimum Spanning Tree

• Problem:

given a <u>connected</u>, <u>undirected</u>, <u>weighted</u> graph
 G = (V, E)

- find a spanning tree using edges that connects all nodes with a minimal total weight w(T) = SUM(w[u,v])
  - w[u,v] is the weight of edge (u,v)
- Objectives: we will learn
  - Generic MST
  - Kruskal's algorithm
  - Prim's algorithm

### **Motivation Example**

- Problem definition
  - A town has a set of houses and a set of roads
  - Each road connects 2 and only 2 houses
  - A road connecting houses u and v has a repair cost w(u, v)
- Goal: Repair enough (and no more) roads such that
  - everyone stays connected: can reach every house from all other houses, and
  - The total repair cost is minimum

#### Model as a graph

- The problem can be modeled as a graph
  - Undirected weighted graph G = (V, E).

- Weight w(u, v) on each edge  $(u, v) \in E$ .

• Find  $T \subseteq E$ , such that

- T connects all vertices (T is a spanning tree)

$$w(T) = \sum_{(u,v)\in T} w(u,v)$$
 is minimized.

• A spanning tree whose weight is minimum over all spanning trees is called a minimum spanning tree, *MST*.

#### Growing a minimum spanning tree

- Building up the solution
  - We will build a set A of edges
  - Initially, A has no edges.
  - As we add edges to A, maintain a loop invariant
- Loop invariant: A is a subset of some MST
  - Add only edges that maintain the invariant
  - Definition: If A is a subset of some MST, an edge
     (u, v) is safe for A, if and only if A ∪ {(u, v)} is also a subset of some MST
  - So we will add only safe edges

### Generic MST algorithm

GENERIC-MST(G, w)  $A = \emptyset$ while A is not a spanning tree find an edge (u, v) that is safe for A  $A = A \cup \{(u, v)\}$ return A

#### Correctness

- Use the loop invariant to show that this generic algorithm works.
  - <u>Initialization</u>: The empty set trivially satisfies the loop invariant.
  - <u>Maintenance</u>: Since we add only safe edges, A remains a subset of some MST.
  - <u>Termination</u>: All edges added to A are in an MST, so A is a spanning tree that is also an MST, when we stop

### Definitions

- Let  $S \subset V$  (vertex set);  $A \subseteq E$  (edge set).
- A cut (S, V S) is a partition of vertices into two disjoint sets: S and V-S
- Edge (u, v) ∈ E crosses the cut (S, V−S) if one endpoint is in S and the other is in V−S.
- A cut **respects** edge set A, if and only if no edge in A crosses the cut.
- An edge is a light edge crossing a cut, if and only if its weight is minimum over all edges crossing the cut.
  - For a given cut, there can be > 1 light edge crossing it.

### Theorem

- Let edge set A be a subset of some MST
- (S, V S) be a cut that respects edge set A
   No edges in A crosses the cut
- (u, v) be a light edge crossing cut (S, V −S).
- Then, (u, v) is safe for A.
- Proof
  - Let tree T be an MST that includes edge set A
  - If T contains edge (u, v), done.
  - So, now assume that T does not contain edge (u, v)
  - We'll construct a different MST T' that includes  $A \cup \{(u, v)\}$ .

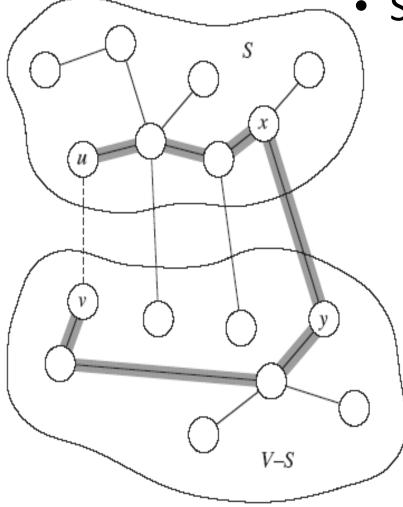
10

# Proof

- Recall: a tree has a unique path between each pair of vertices (why?).
  - Since T is an MST, it contains a unique path p between u and v.
  - Path p must cross the cut (S, V-S) once
  - Let (x, y) be an edge of p that crosses the cut
- As (u,v) is a light edge, we have  $w(u,v) \le w(x,y)$
- Since the cut respects A, edge (x, y) is not in A
- We can build tree T' from T
  - Remove (x, y): Breaks T into two components.
  - Reconnects them with edge  $(u,v) \rightarrow T'$

Proof

Except for the dashed edge (u, v), all edges shown are in T
Shaded edges are the path p



# Proof

- So T' = T  $\{(x, y)\} \cup \{(u, v)\}.$
- $\rightarrow$  T' is another spanning tree
- $w(T') = w(T) w(x, y) + w(u, v) \le w(T)$ 
  - since  $w(u, v) \le w(x, y)$
  - − Since (1) T' is a spanning tree, (2) w(T') ≤ w(T), and (3) T is an MST  $\rightarrow$  T' must be an MST
- Need to show that  $A \cup \{(u, v)\} \subset T'$ 
  - $-A \subseteq T$  and  $(x, y) \notin A \qquad \Rightarrow A \subseteq T \{(x, y)\}$

 $- A \cup \{(u, v)\} \subseteq \mathsf{T} - \{(\mathsf{x}, \mathsf{y})\} \cup \{(u, v)\} = \mathsf{T}'$ 

- Since T' is an MST, edge (u, v) is safe for A.

### MST: optimal substructure

- MSTs satisfy the optimal substructure property: an optimal tree is composed of optimal subtrees
  - Let T be an MST of G with an edge (u, v) in the middle
  - Removing (u, v) partitions T into two trees T<sub>1</sub> and T<sub>2</sub>
  - Claim:  $T_1$  is an MST of  $G_1 = (V_1, E_1)$ , and  $T_2$  is an MST of  $G_2 = (V_2, E_2)$
- Proof: w(T) = w(u, v) + w(T<sub>1</sub>) + w(T<sub>2</sub>) (There can't be a better tree than T<sub>1</sub> or T<sub>2</sub>, or T would be suboptimal)

# Corollary

- If C = (V<sub>C</sub>, E<sub>C</sub>) is a connected component in the forest  $G_A = (V, A)$
- (u, v) is a light edge connecting C to some other component in  $\rm G_A$

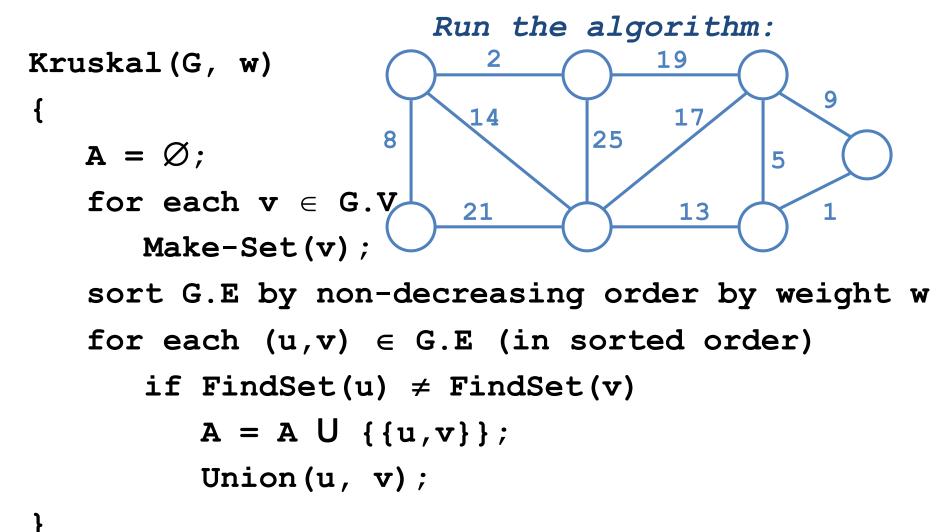
- i.e.,(u,v) is a light edge crossing the cut  $(V_c, V-V_c)$ 

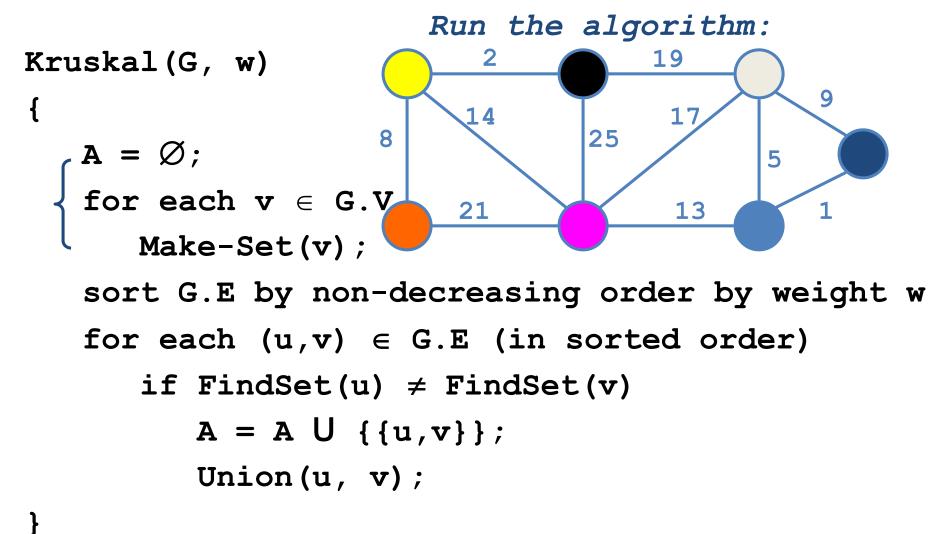
- Then, edge (u, v) is safe for A.
- **Proof:** Set  $S = V_c$  in the theorem.
  - This naturally leads to the Kruskal's algorithm

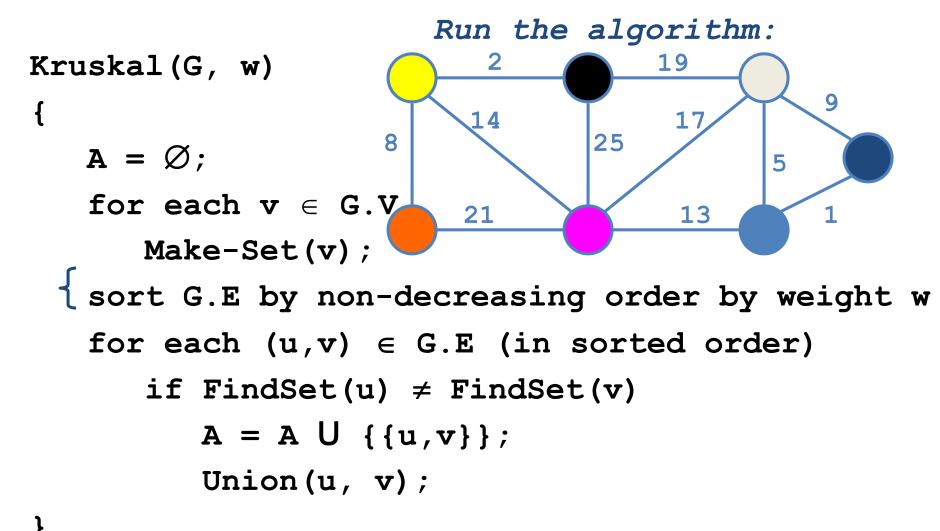
- Starts with each vertex being its own component
- Repeatedly merges two components into one by choosing the light edge that connects them
- Scans the set of edges in monotonically increasing order by weight
- Uses a disjoint-set data structure to determine whether an edge connects vertices in different components.

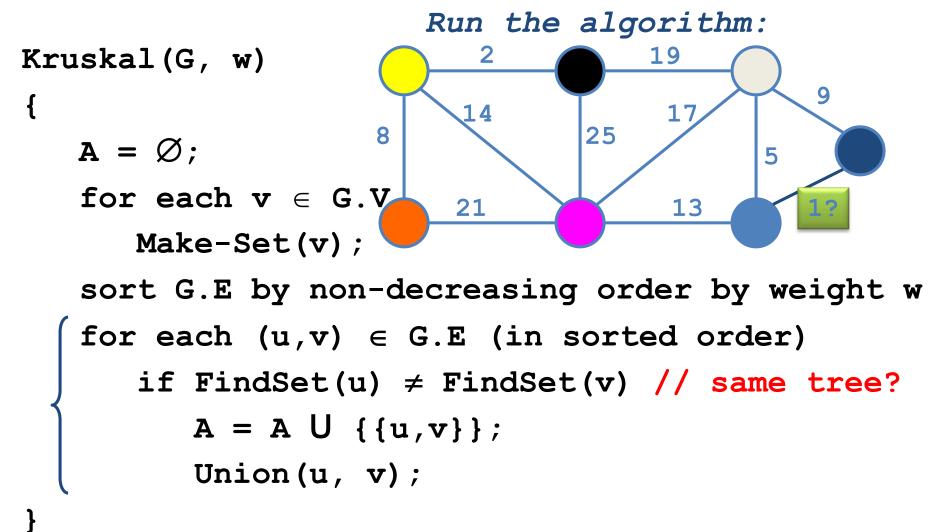
### Disjoint Sets Data Structure

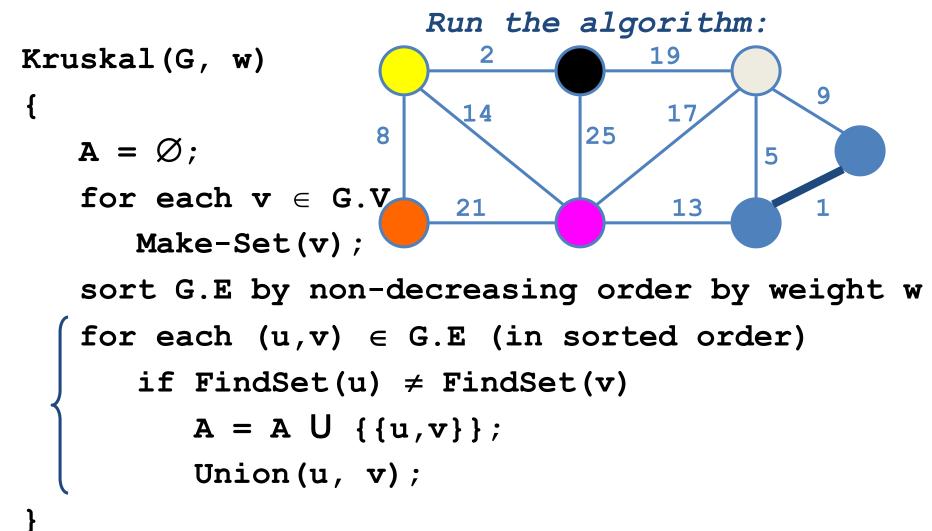
- A disjoint-set is a collection C ={S<sub>1</sub>, S<sub>2</sub>,..., S<sub>k</sub>} of distinct dynamic sets
- Each set is identified by a member of the set, called representative.
- Disjoint set operations:
  - MAKE-SET(x): create a new set with only x
    - assume x is not already in some other set.
  - UNION(x,y): combine the two sets containing x and y into one new set.
    - A new representative is selected.
  - FIND-SET(x): return the representative of the set containing x.

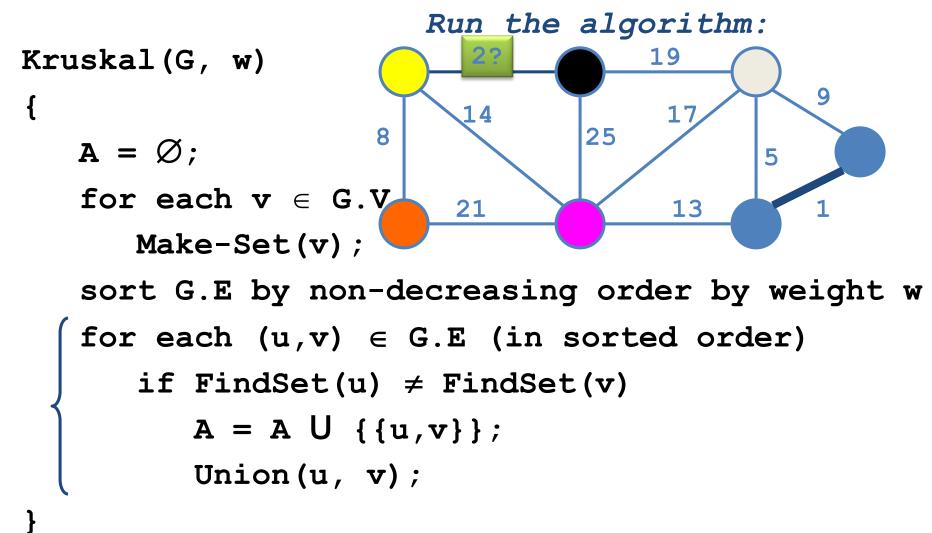


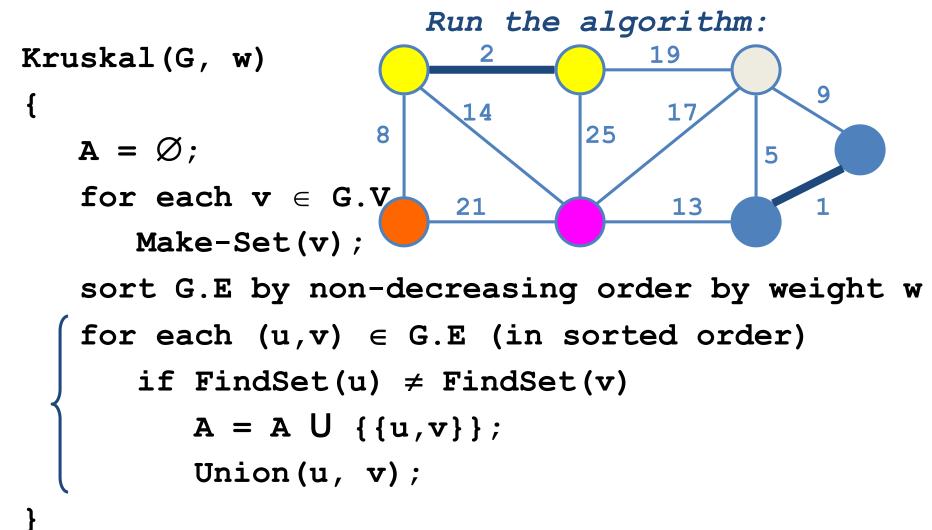


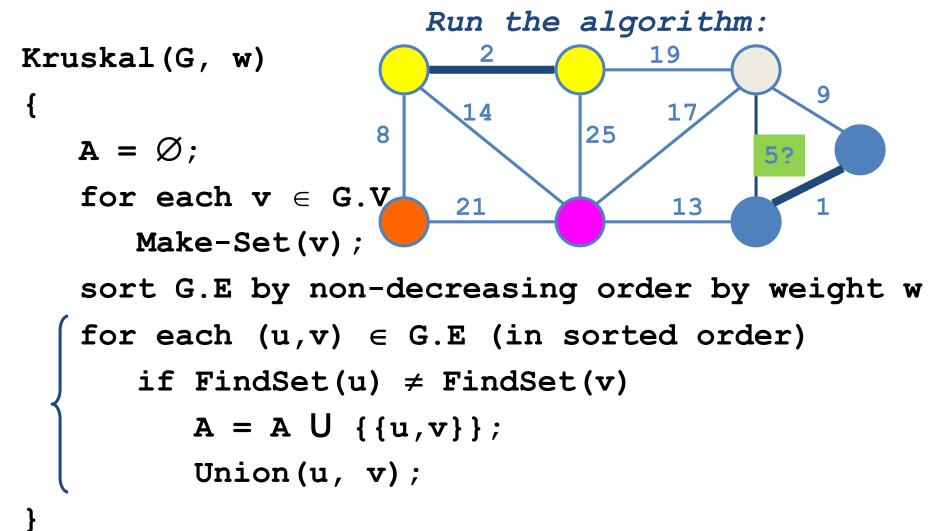


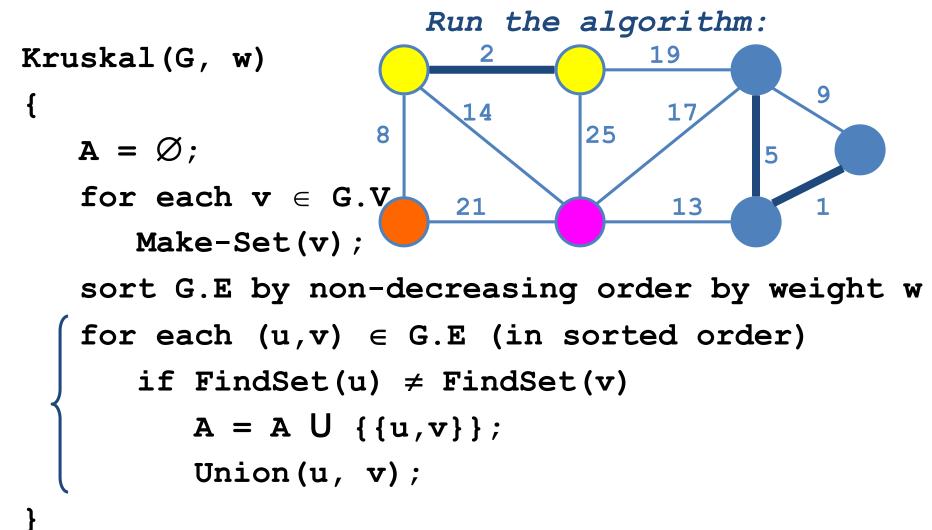


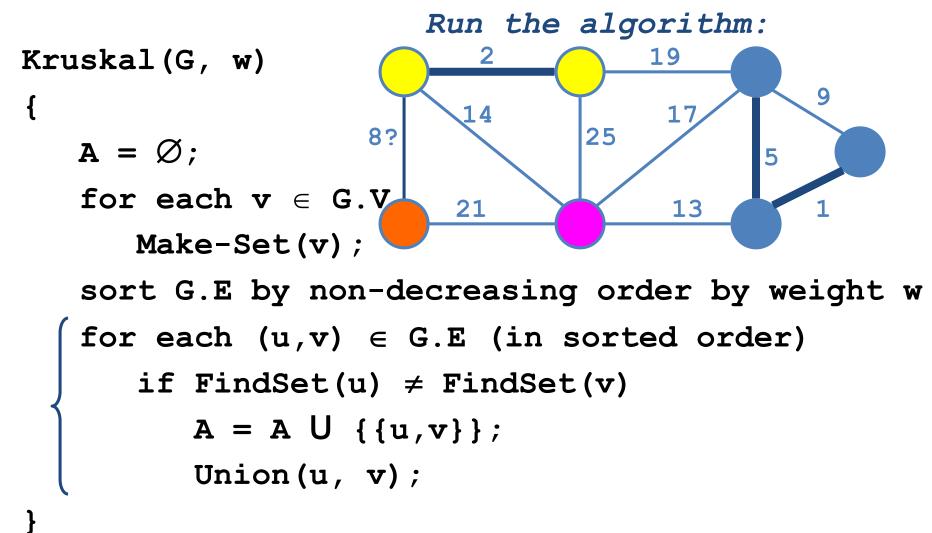


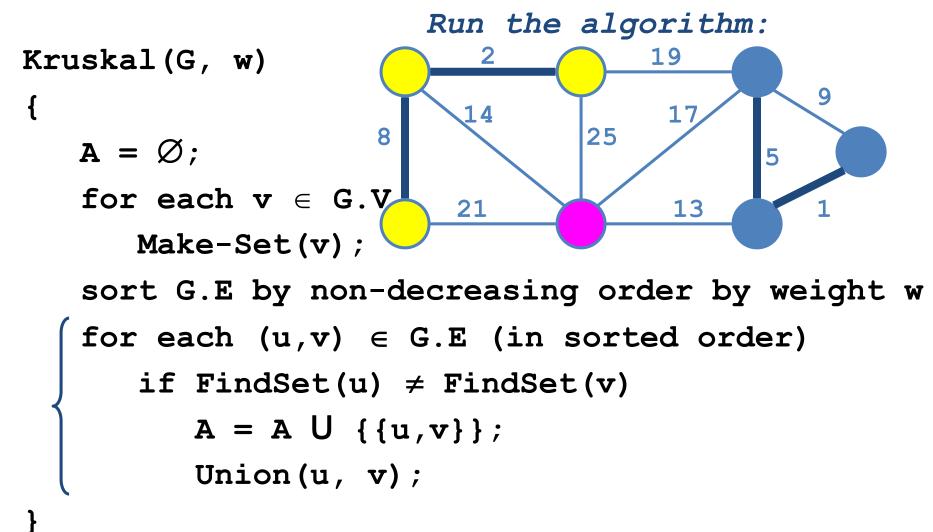


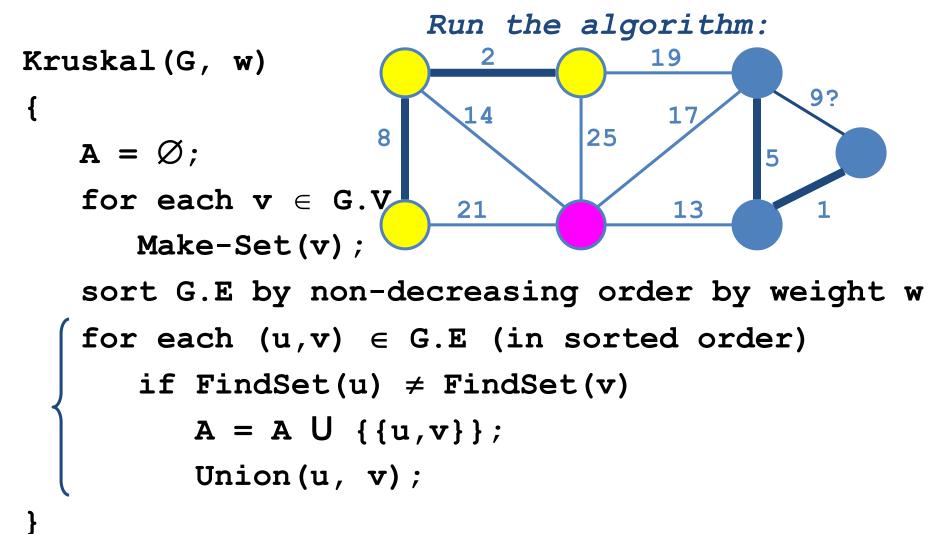


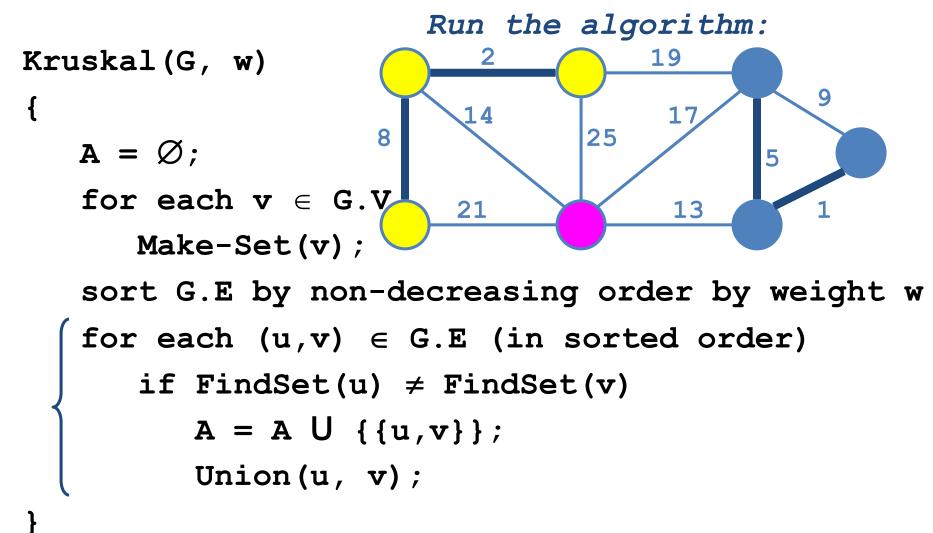


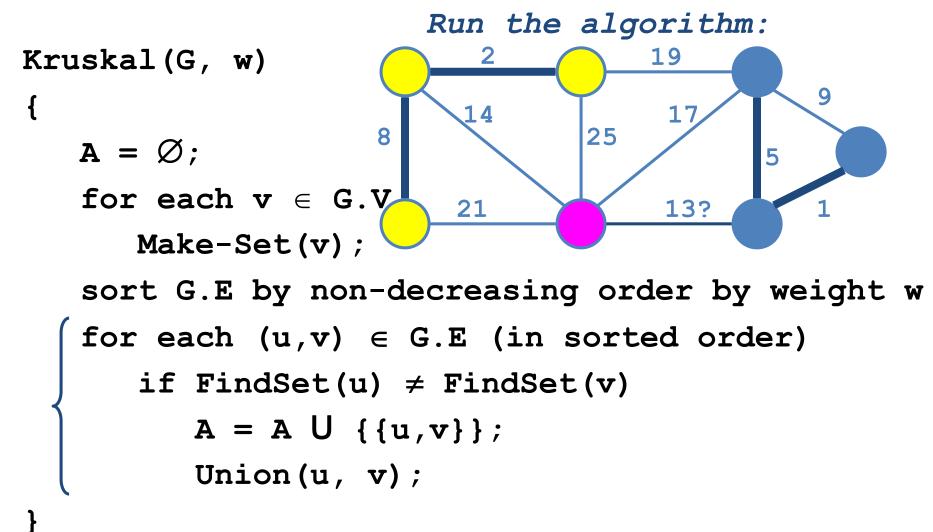


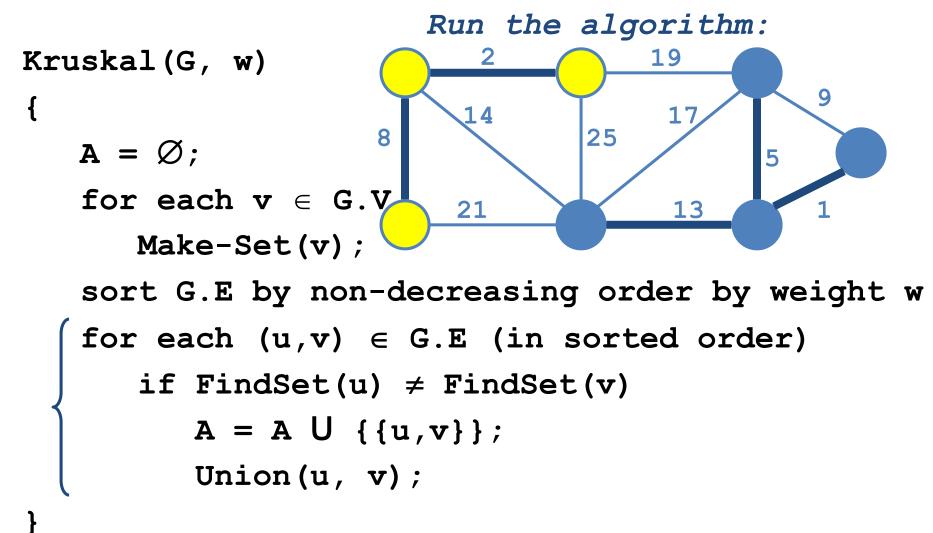


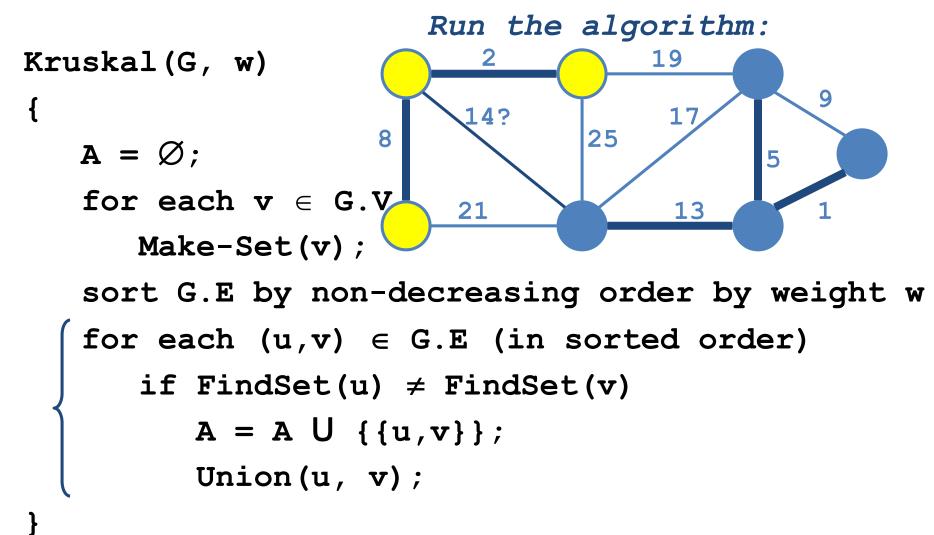


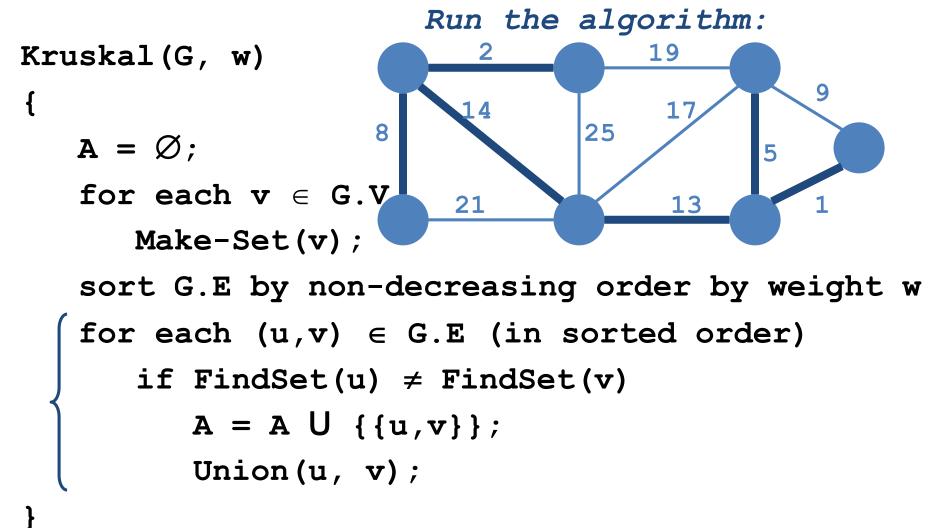


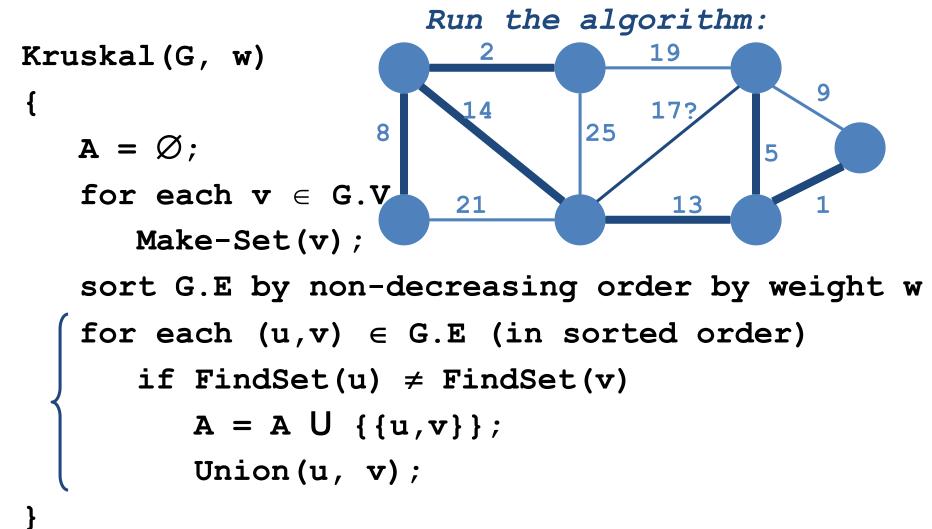


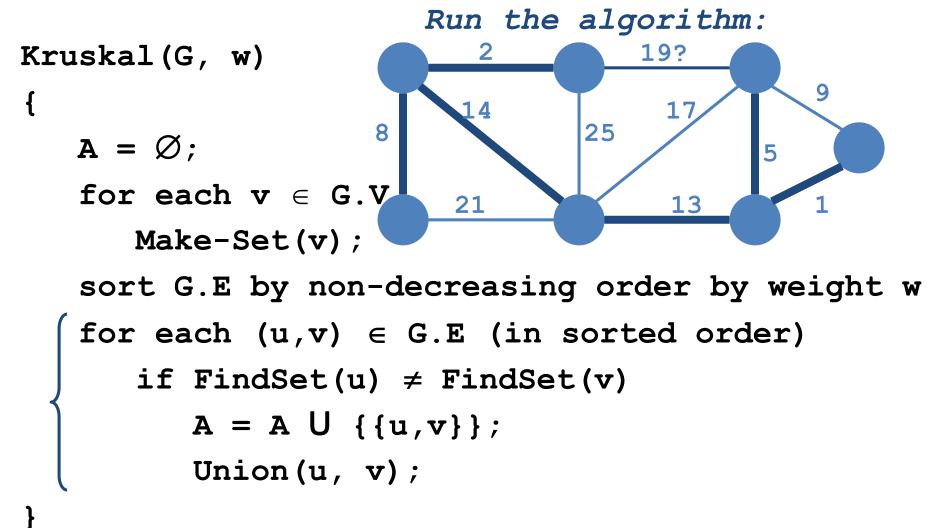


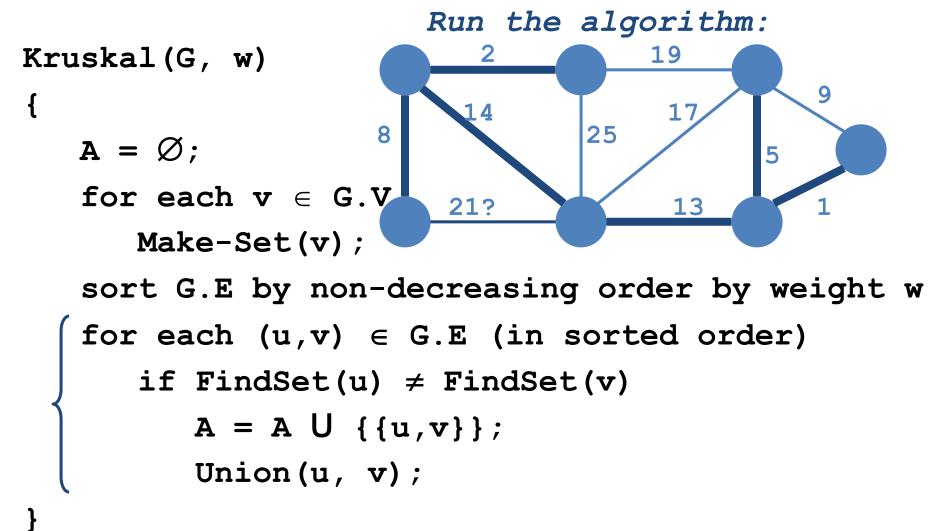




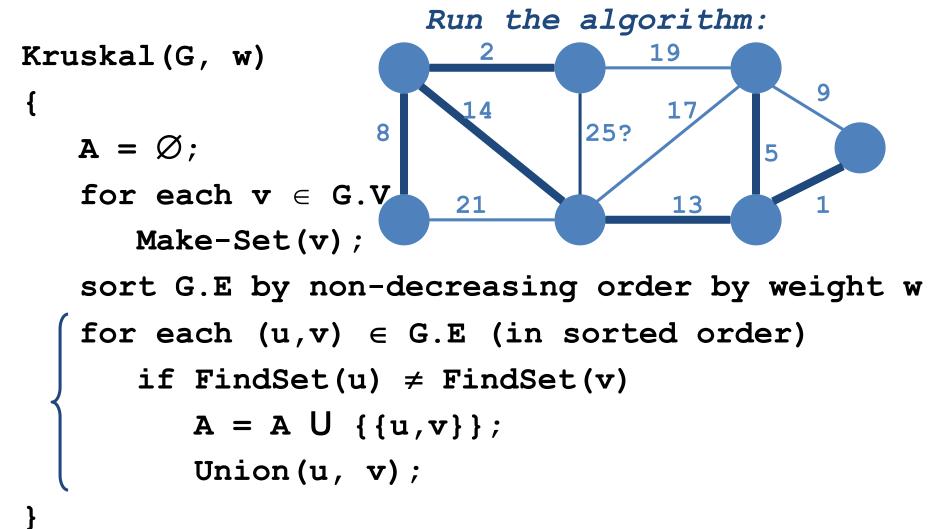




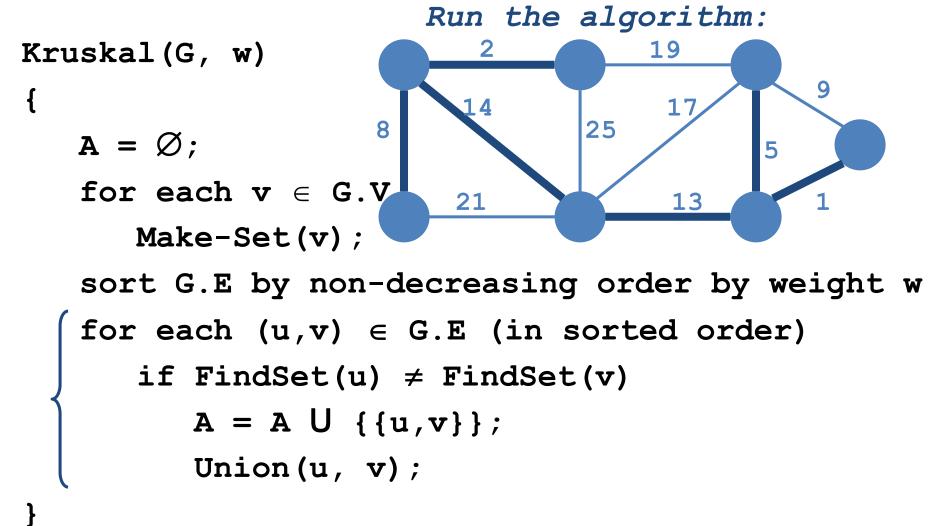




### Kruskal's Algorithm



### Kruskal's Algorithm: Done



# Correctness Of Kruskal's Algorithm

- Sketch of a proof: this algorithm produces an MST of T
  - Assume algorithm is wrong: result is not an MST
  - Then, algorithm adds a wrong edge at some point
  - If it adds a wrong edge, there must be another lower weight edge
  - But algorithm chooses lowest weight edge at each step.
     Contradiction

### Kruskal's Algorithm

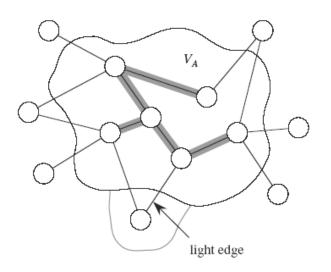
Kruskal(G, w)	What will affect the running time?	
{	Initialize A	<b>O(1)</b>
$\mathbf{A} = \emptyset;$	1 <sup>st</sup> FOR loop  V	MakeSet() calls
,	Sort	O(E lgE)
for each $\mathbf{v} \in \mathbf{G}.\mathbf{V}$	FINDSET()/Union()	O(E) calls
<pre>Make-Set(v) ;</pre>		
sort G.E by non-c	decreasing order	by weight w
for each $(u,v) \in$	G.E (in sorted o	rder)
if FindSet(u) $\neq$ FindSet(v)		
$A = A U \{ \{ u \} \} \}$	u,v}};	
Union(u, v)	;	

}

### Kruskal's Algorithm: Running Time

- Initialize A: O(1)
- First for loop: |V| MAKE-SETs
- Sort E: O(E lg E)
- Second for loop: O(E) FIND-SETs and UNIONs
- O(V) +O (E α(V)) + O(E lg E)
  - − Since G is connected,  $|E| \ge |V| 1 \Rightarrow O(E \alpha(V)) + O(E \lg E)$
  - $\alpha(|V|) = O(|g V) = O(|g E)$
  - Therefore, the total time is O(E lg E)
  - $|E| \le |V|^2 \Rightarrow |g| |E| = O(2 |g|V) = O(|g|V)$
  - Therefore, O(E lg V) time

- Build a tree A
  - Starts from an arbitrary "root" r.
  - At each step, find a <u>light edge</u> crossing the cut  $(V_A, V V_A)$ , where  $V_A$  = vertices that A is incident on.
  - Add this light edge to A.
- GREEDY CHOICE: add min weight to A



[Edges of A are shaded.]

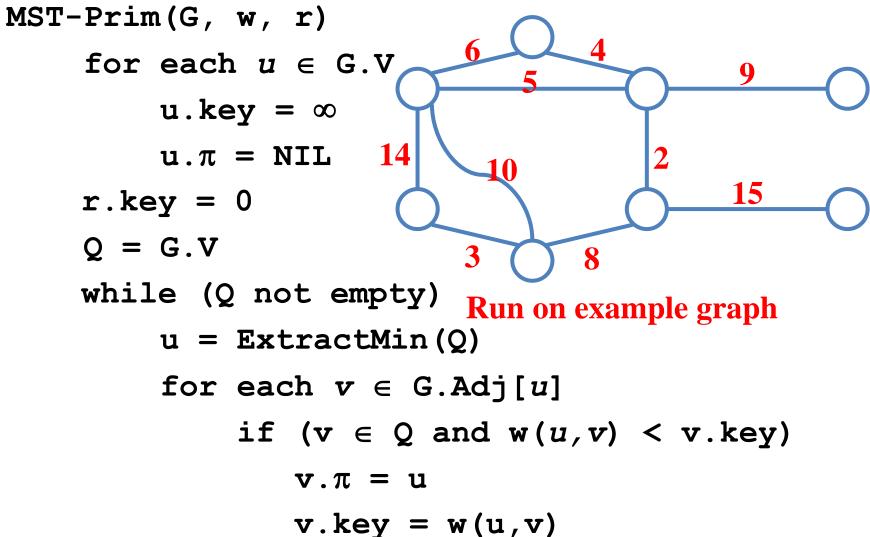
#### How to find the light edge quickly?

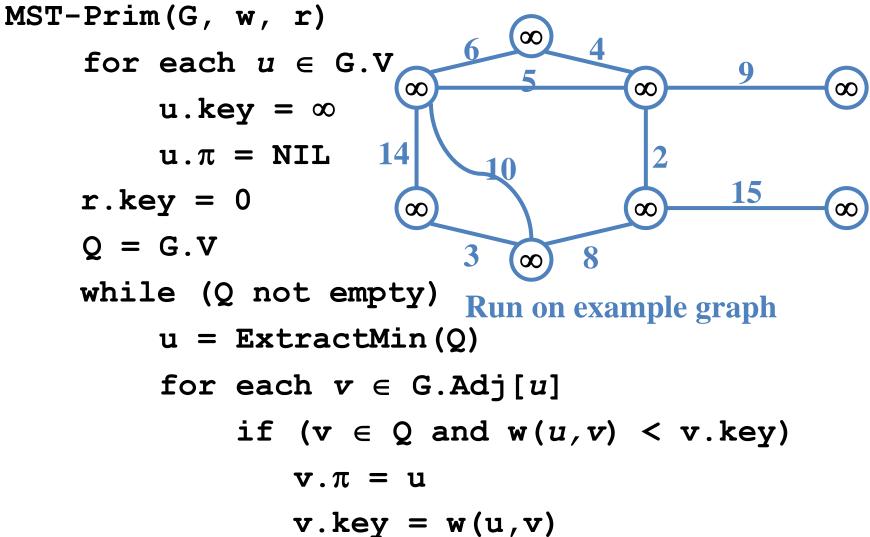
- Use a priority queue Q
  - Each object is a vertex in  $V-V_A$
  - Key of v is the minimum weight of any edge (u, v), where  $u \in V_A$
  - the vertex returned by EXTRACT-MIN is v
    - such that there exists  $u \in V_A$ , and edge (u, v) is a light edge crossing  $(V_A, V-V_A)$
- Key of v is  $\infty$ , if v is not adjacent to any vertices in  $V_A$

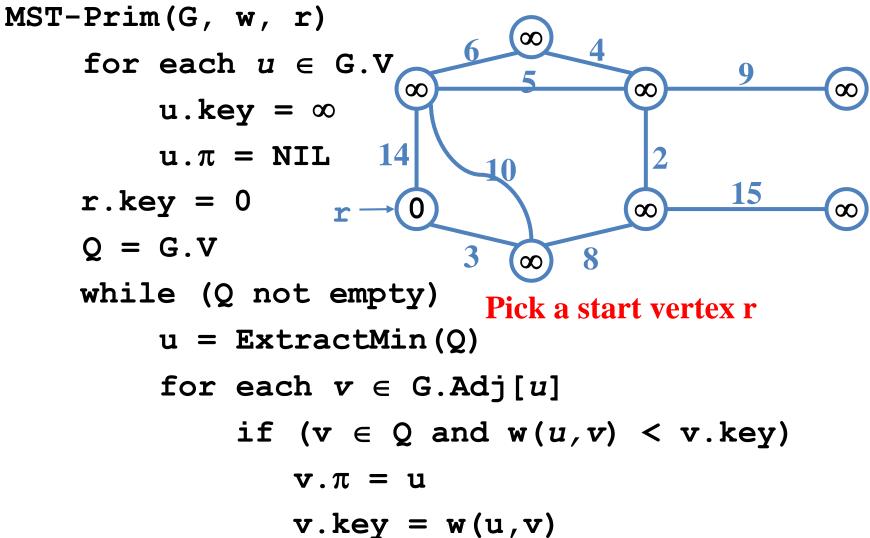
#### How to find the light edge quickly?

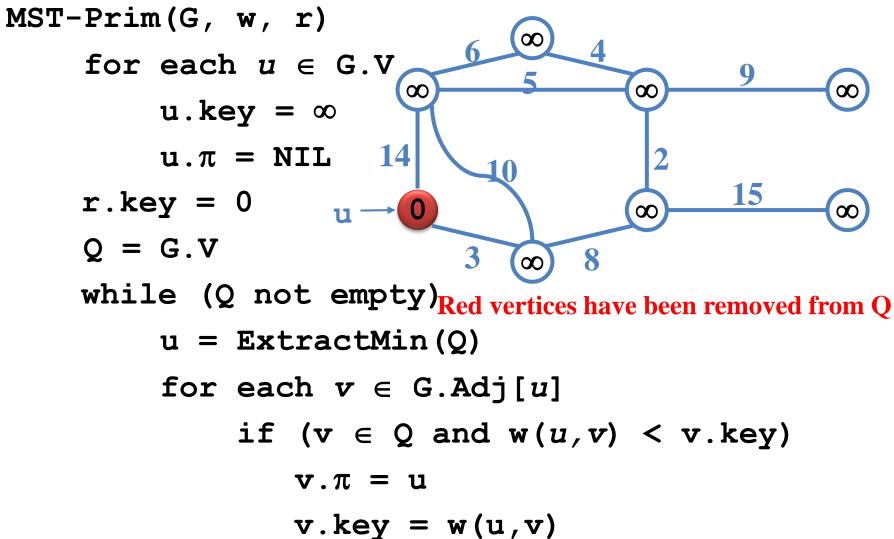
- The edges of A form a rooted tree with root r
  - *r* is given as an input to the algorithm, but it can be any vertex
  - Each vertex knows its parent in the tree by the attribute  $v.\pi$  = parent of v
  - $-\pi[v] = NIL$ , if v = r or v has no parent.
  - As the algorithm progresses,  $A = \{(v, v.\pi) : v \in V \{r\} Q\}$

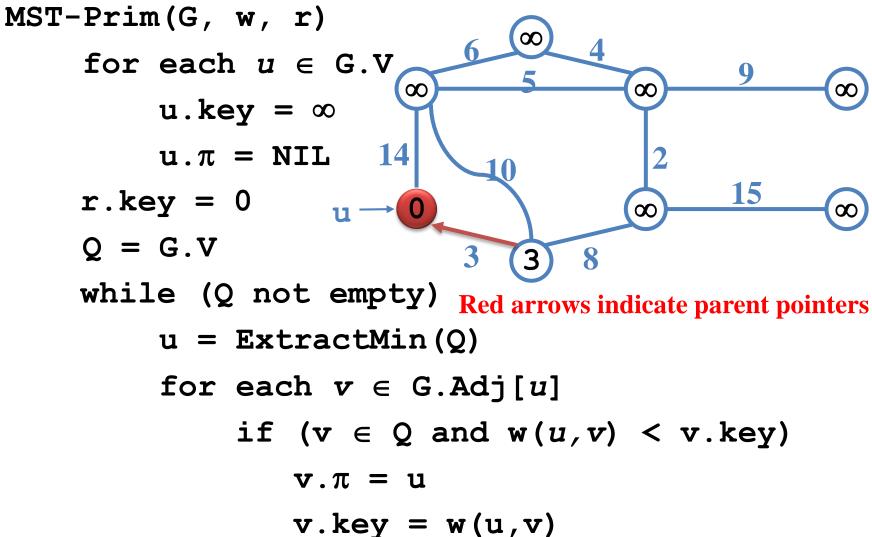
```
MST-Prim(G, w, r)
     for each u \in G.V
          u.key = \infty
           u.\pi = NIL
     r.key = 0
     Q = G.V
     while (Q not empty)
          u = ExtractMin(Q)
          for each v \in G.Adj[u]
                if (v \in Q \text{ and } w(u, v) < v. \text{key})
                     \mathbf{v}.\pi = \mathbf{u}
                    v.key = w(u,v)
```

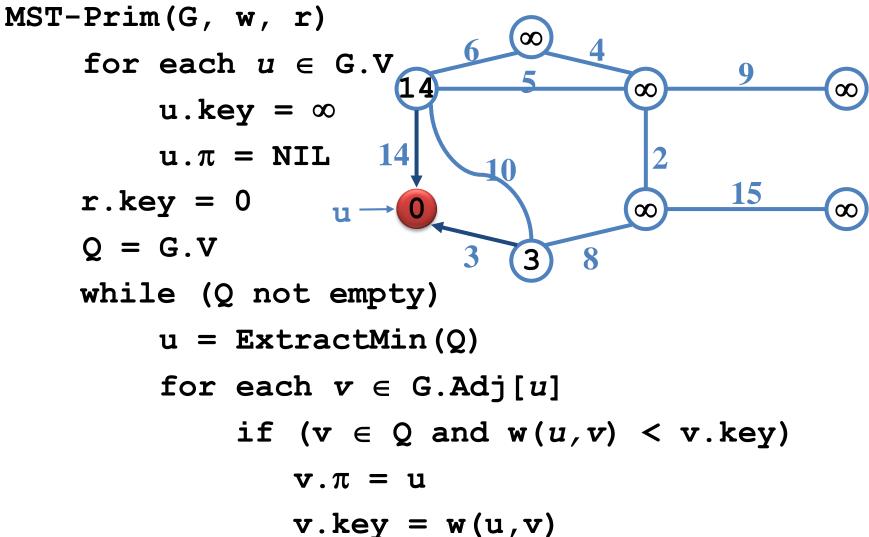


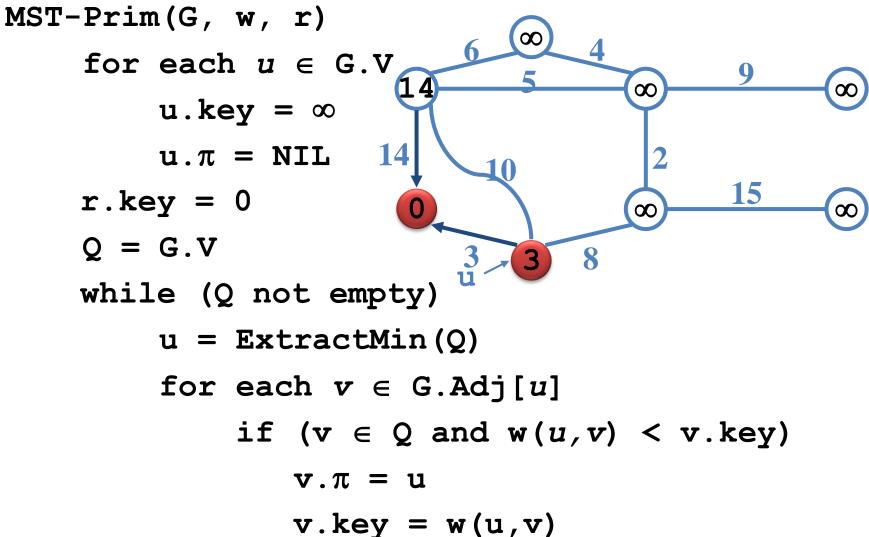


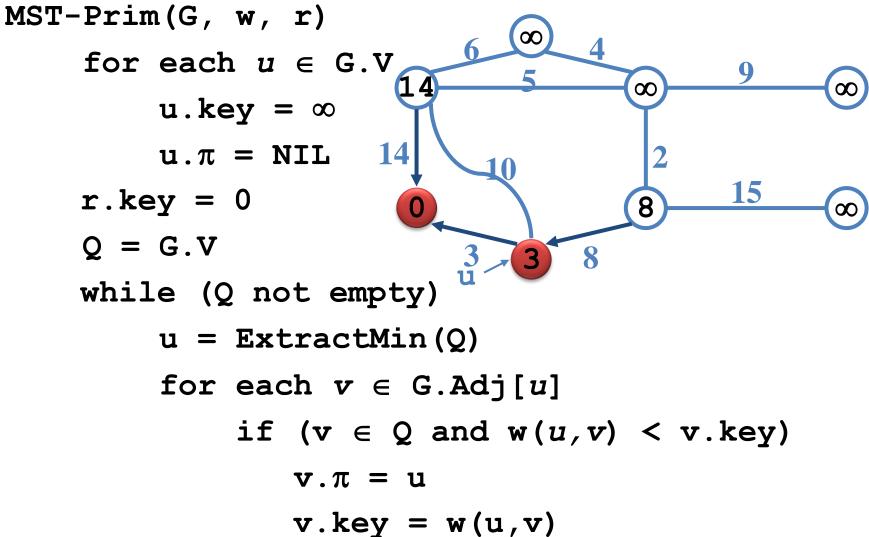


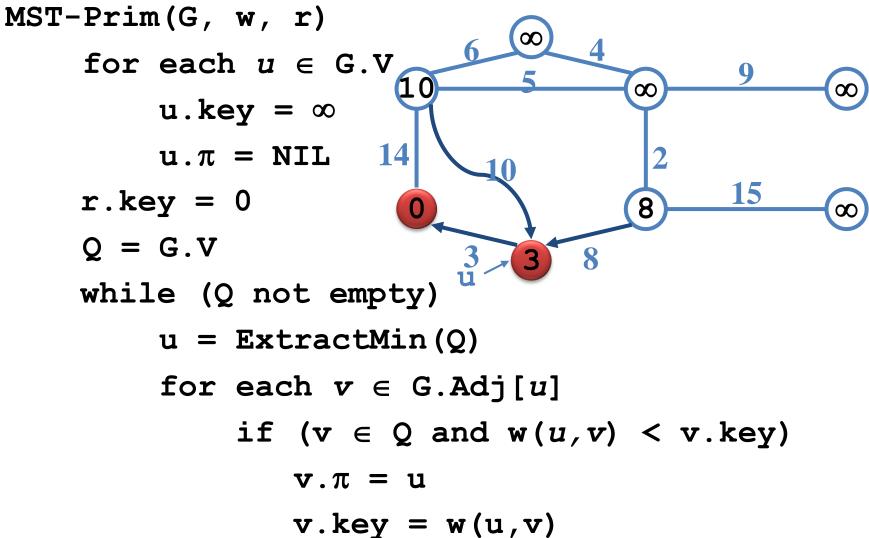


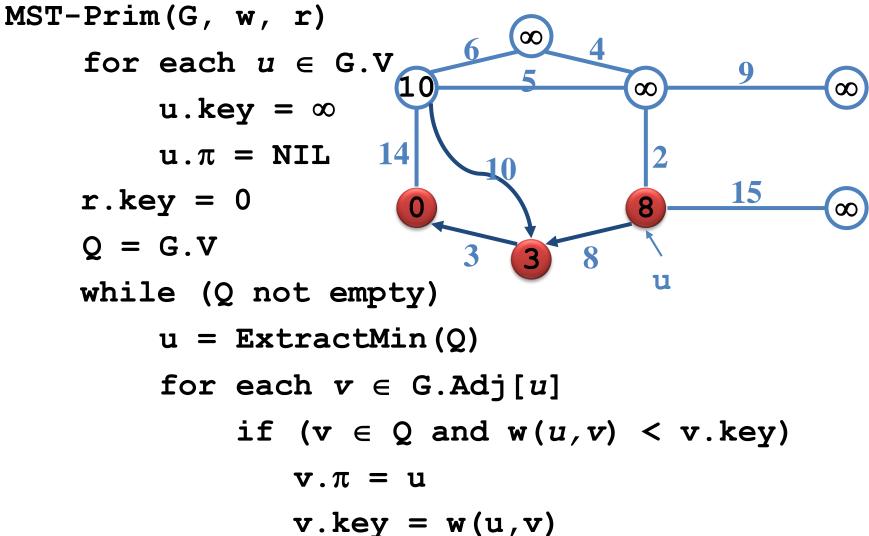


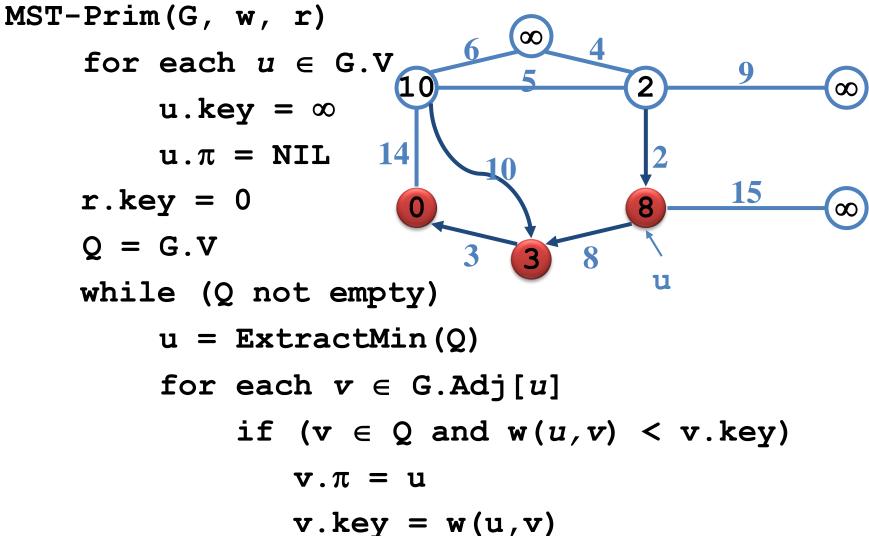


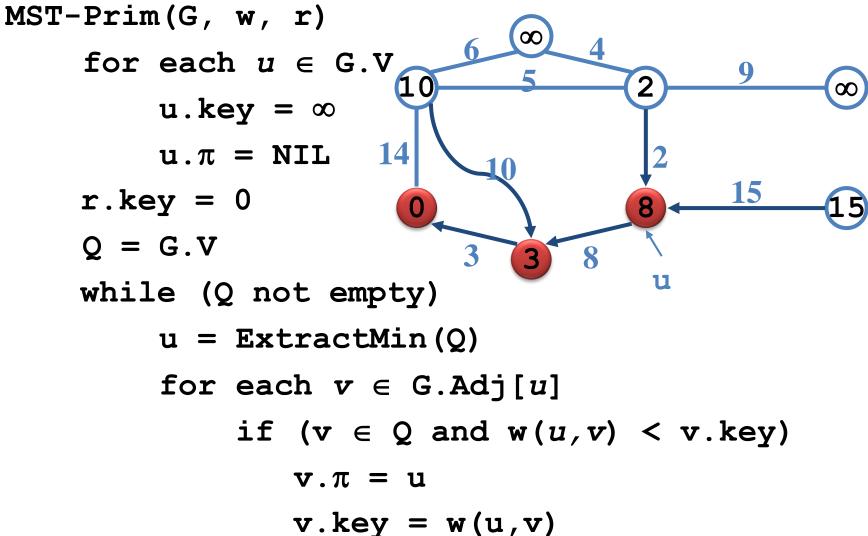


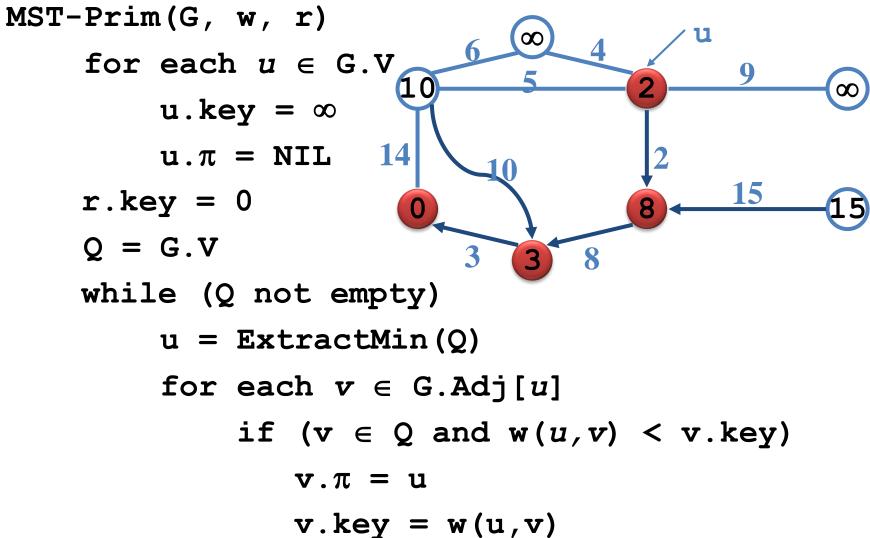


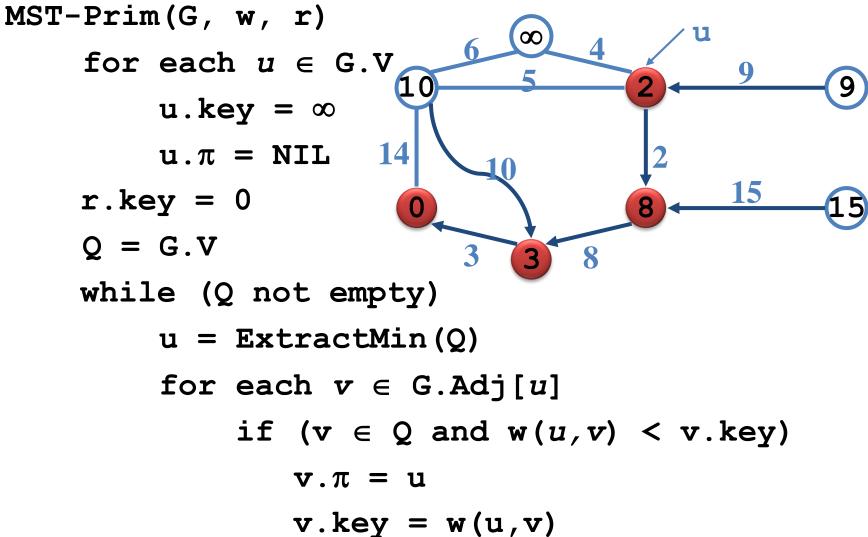


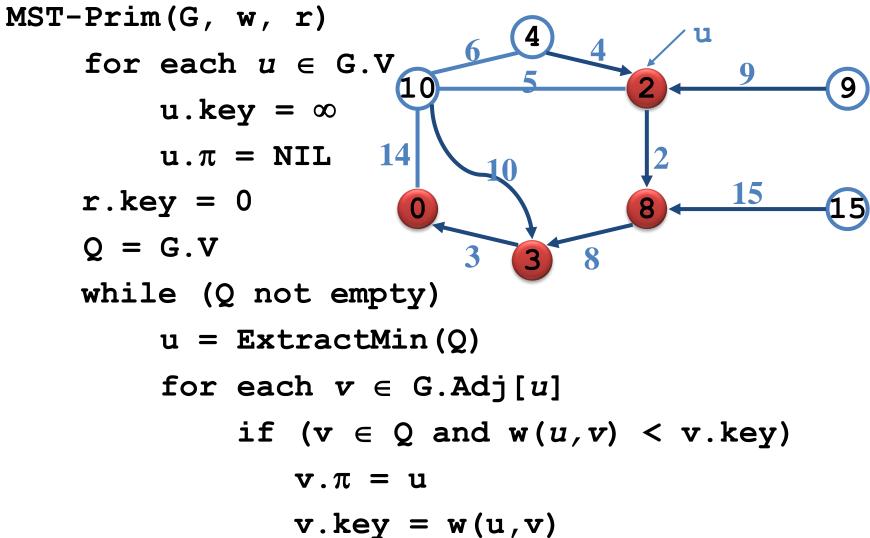


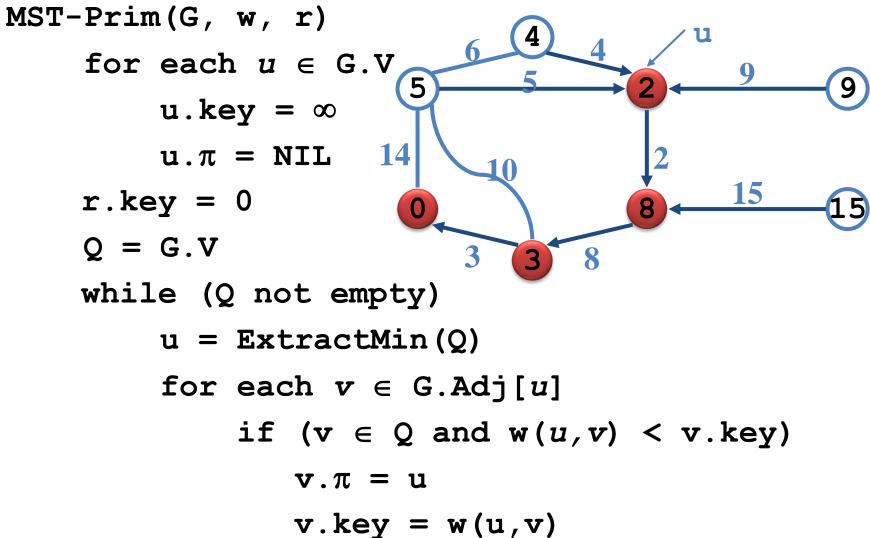


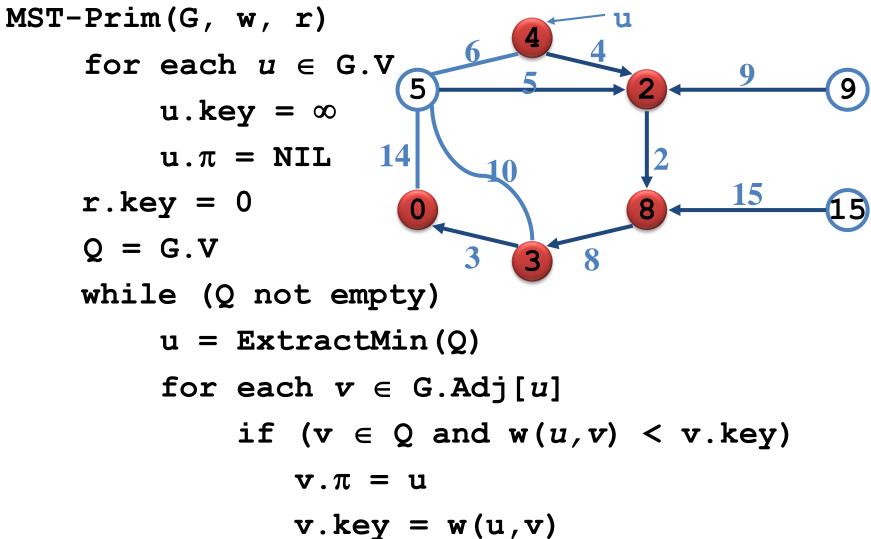


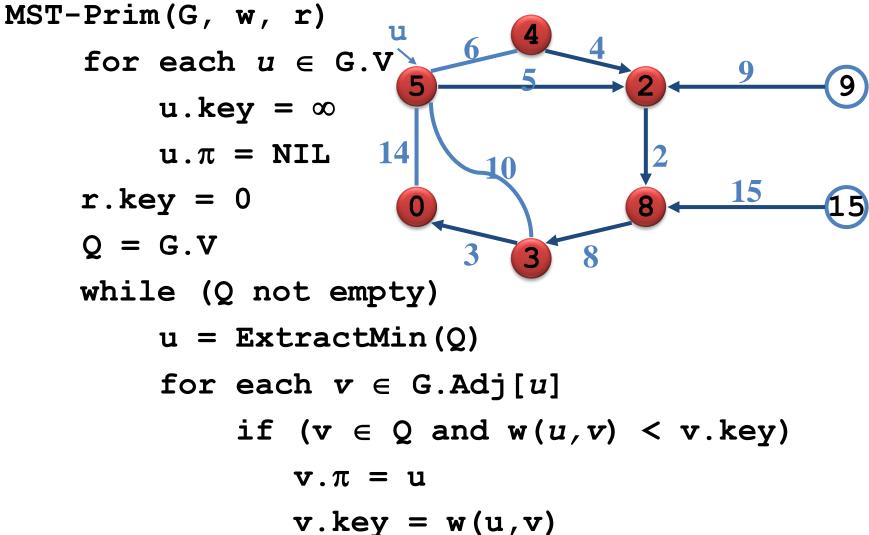


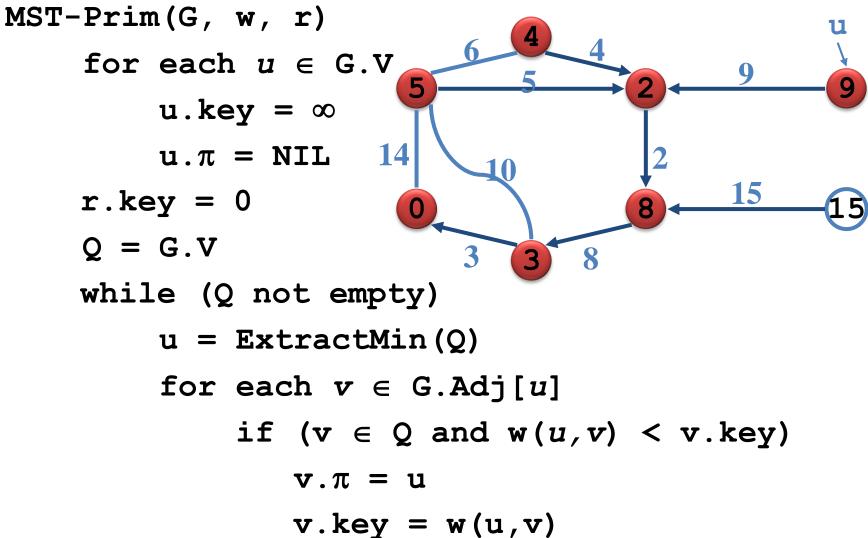


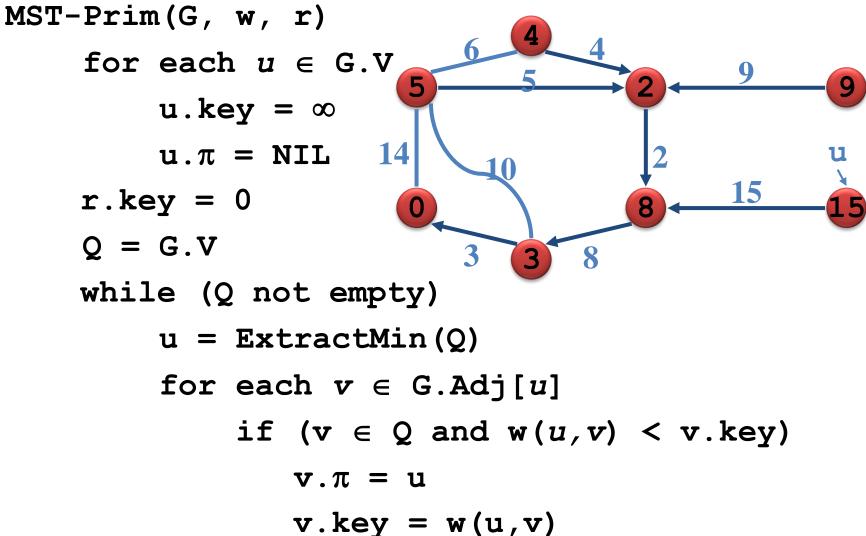












#### **Review: Prim's Algorithm**

```
MST-Prim(G, w, r)
     for each u \in G.V
          u.key = \infty
          u.\pi = NIL
     r.key = 0
                What is the hidden cost in this code?
     Q = G.V
     while (Q not empty)
          u = ExtractMin(Q)
          for each v \in G.Adj[u]
               if (v \in Q \text{ and } w(u, v) < v.key)
                   \mathbf{v}.\pi = \mathbf{u}
                   v.key = w(u,v)
                                                       68
```

### Review: Prim's Algorithm

```
MST-Prim(G, w, r)
     Q = V[G];
     for each u \in Q
          key[u] = \infty;
     key[r] = 0;
     p[r] = NULL;
     while (Q not empty)
          u = ExtractMin(Q);
          for each v \in \operatorname{Adj}[u]
               if (v \in Q \text{ and } w(u, v) < \text{key}[v])
                    p[v] = u;
                    DecreaseKey(v, w(u, v));
```

## Prim's Algorithm: running time

- We can use the BUILD-MIN-HEAP procedure to perform the initialization in lines 1–5 in O(V) time
- EXTRACT-MIN operation is called |V| times, and each call takes O(lg V) time, the total time for all calls to EXTRACT-MIN is O(V lg V)

# Running time (cont'd)

- The for loop in lines 8–11 is executed O(E) times altogether, since the sum of the lengths of all adjacency lists is 2 |E|.
  - Lines 9 -10 take constant time
  - line 11 involves an implicit DECREASE-KEY
     operation on the min-heap, which takes O(lg V)
     time
- Thus, the total time for Prim's algorithm is
   O(V) +O(V lg V) + O(E lg V) = O(E lg V)

– The same as Kruskal's algorithm

## Summary

- We learned
  - Generic MST
  - Kruskal's and Prim's algorithm
- Common mistakes: Don't mix Kruskal's algorithm with Prim's algorithm